

VERSA **BUILT** ROBOTICS



VersaBuilt Robotics
Okuma Robot2CNC Kit

Product No. 5006649



Why Robot2CNC?

VersaBuilt Robotics Robot2CNC provides a simple and easy way to communicate with CNCs.

This communication kit provides the ability to run any program on a CNC, cycle start the CNC, and check to see if the program completed successfully.

The Robot2CNC allows testing robot and CNC independently to enable easy proving out of automated processes.

The value this kit provides to a programmer:

- Enables creation of robot programs based on a part number (or dynamically) to easily change between different types of parts
- Enables running multiple operations on a single part
- Enables other programs to run as commanded by the robot (wash program or table load program)

The value this kit provides to an installer:

- Simple installation
- Isolated testing
- Defined API
- Compatible across multiple brands of CNCs



Overview

The purpose of this document is to detail the installation steps and usage of the Okuma Robot2CNC Kit

The Okuma Robot2CNC Kit allows the Robot2CNC to:

- Select CNC programs on Okuma CNC Controllers
- Cycle Start the Okuma CNC
- Receive results back from the CNC to indicate successful CNC program completion
- Read and Write Macro Variables on the Okuma CNC

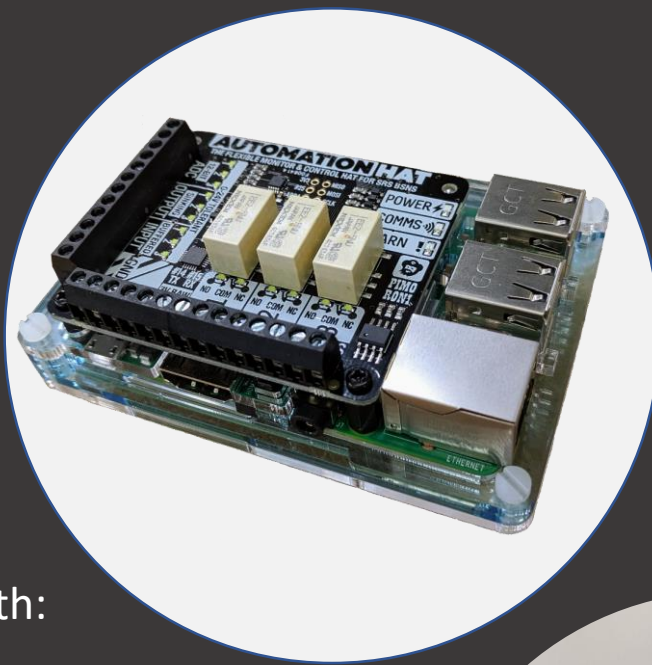
Functionality of the Okuma Robot2CNC Kit is completed by:

- Sending TCP/IP packets between the Robot2CNC appliance and Okuma CNC controller through an Ethernet cable (or over Wi-Fi)
- The CNC is started through a signal from the Robot2CNC appliance to energize the CNC cycle start button, by way of a relay
- Signaling the completion of CNC programs from the CNC to the Robot2CNC is completed with software running on the CNC



In The Box

- Robot2CNC Appliance
- USB Flash Drive (5003885) with:
 - Software for CNC
 - Manuals
 - Software for Robots
- Ethernet Cables (5003974) qty 2
- Ethernet to USB dongle (5006782)
- Wiring for cycle start connection (5003967)



Requirements

Okuma Requirements



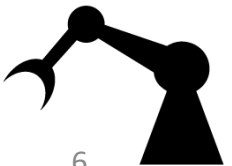
Okuma Requirements

Version 1.0 of Robot2CNC only supports Okuma Mills (MC)

Note: Please contact VersaBuilt Robotics if installing on a Lathe

Okuma Controller OS Requirements

- OSP-P300
- Windows XP or Windows 7
- ThincAPI version 1.17.2 or newer



Steps

Connect

- Ethernet Cable from Robot2CNC to Okuma CNC Controller
- Cycle Start wires from Robot2CNC to Okuma CNC Controller

Install

- Thinc API version 1.7.2 or newer
- Software on Okuma CNC Controller and configure settings
- Set Robot2CNC for Okuma CNC

Operate

- Send programs from the Robot or the Robot2CNC to the CNC
- Receive job complete signals from the CNC to the Robot2CNC



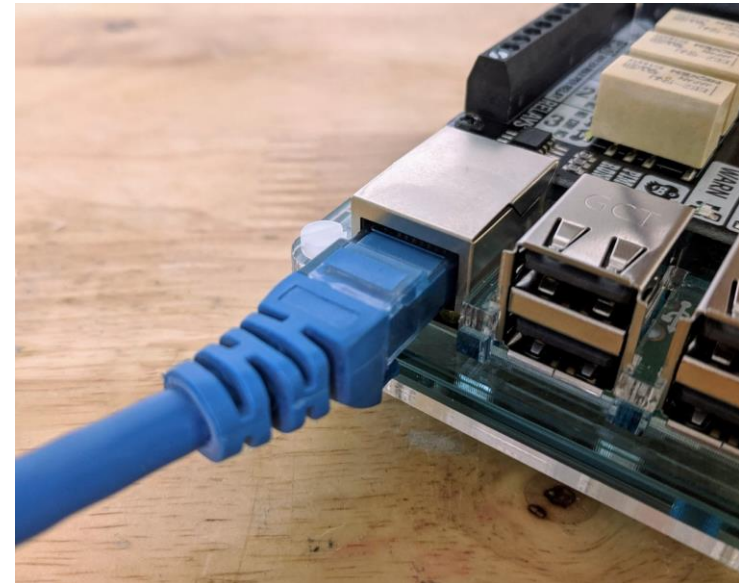
Connect

Ethernet Cable and Cycle Start Relay



Installation of Network Cable

- Connect an Ethernet cable directly to the Robot2CNC Ethernet port
- This port is the Eth0 interface and the IP Address will default to 192.168.50.1



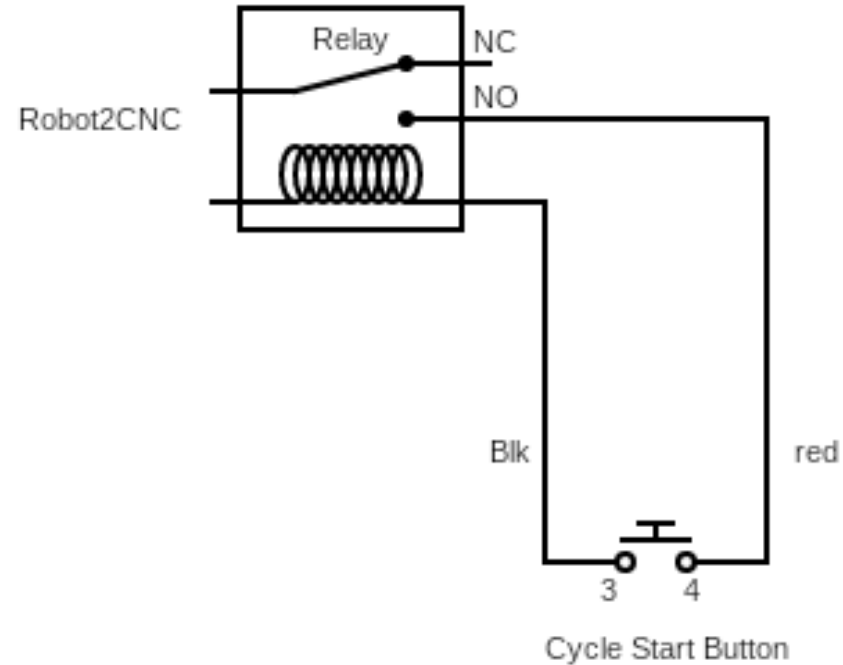
Installation of Network Cable

- Connect an Ethernet cable from the Robot2CNC Appliance to the Okuma CNC – Contact Okuma Dealer for help locating in cabinet network connections.



Cycle Start Wiring

Connecting to Okuma CNC Controller





1. Make sure CNC is powered off
2. Rotate Okuma Control Panel to show back of panel
3. Remove the back cover panel on the Control Panel by unscrewing the 4 fasteners



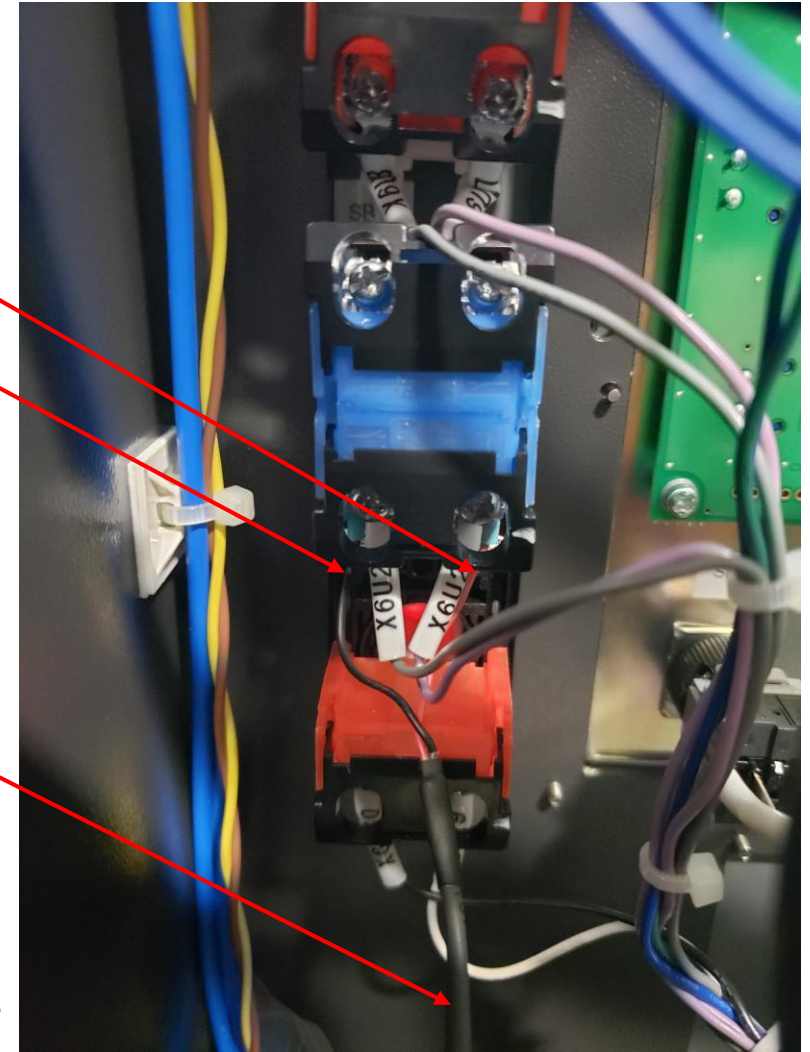
Connect Cycle Start Relay to Okuma CNC Controller





Connect the VersaBuilt Robotics Cycle Start wires with black cable and red cable (note: polarity does not matter)

5. Locate the Cycle Start Button
6. Remove backing with flathead screwdriver
7. Connect the two wires from the yellow cable to the terminals on the Button. Polarity does not matter. Either wire can go to either terminal.



Connect Cycle Start Relay to Okuma CNC Controller



8. Route the cable through cable routing pipe
9. Connect wires to Robot2CNC appliance as shown on the next page
10. Put back sheet metal cover panel and fasten the 4 screws

**note: some hardware may vary depending on CNC model and year*



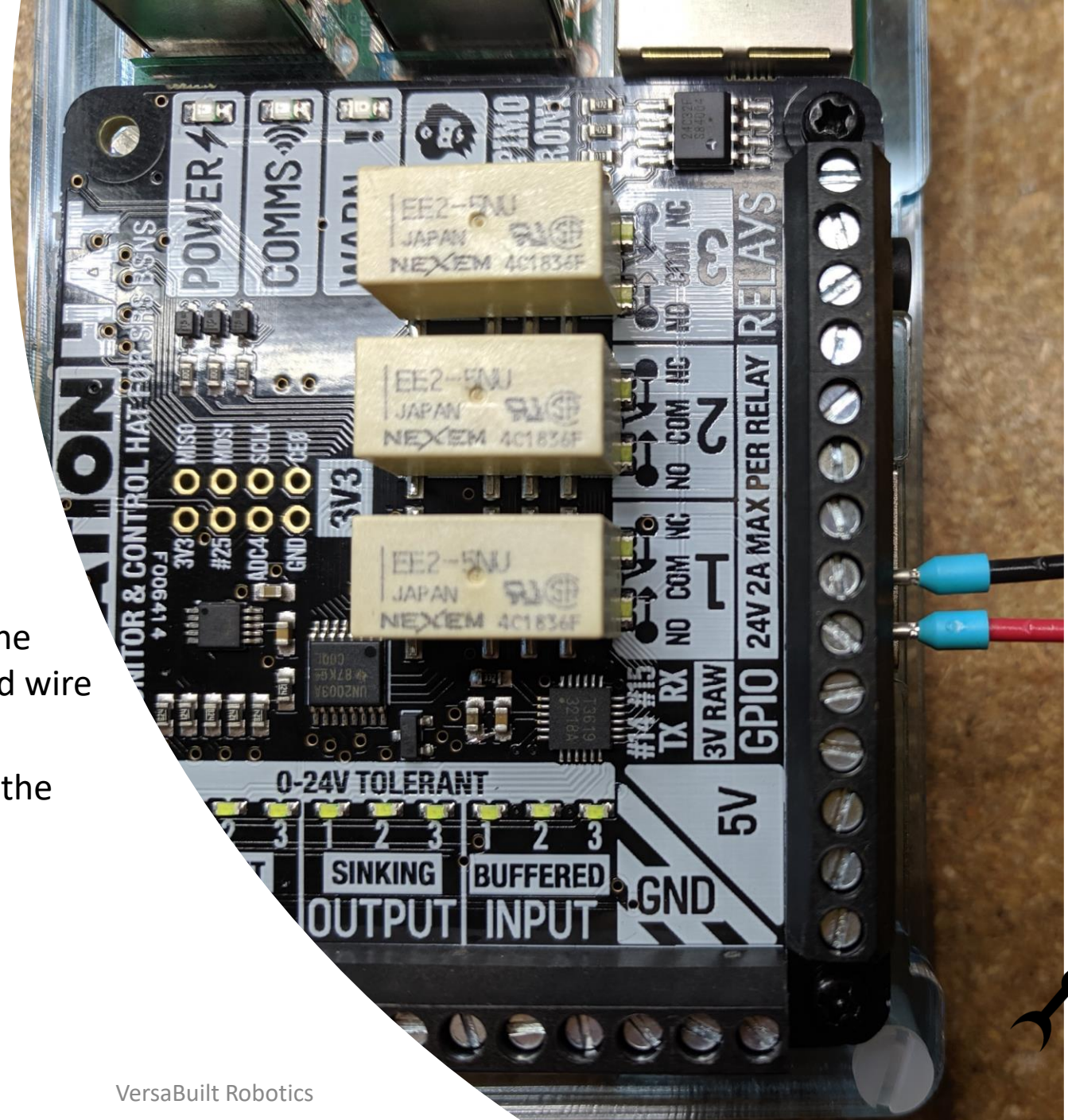
Connect Cycle Start Relay to Okuma CNC Controller



Connecting to Robot2CNC

Tools Needed:

- Small flathead screwdriver
1. Locate relay 1 on the Robot2CNC
 2. Using the flathead screwdriver, loosen the terminal marked NO and connect the red wire and tighten it down
 3. Repeat the process for the black wire in the terminal marked COM



Install

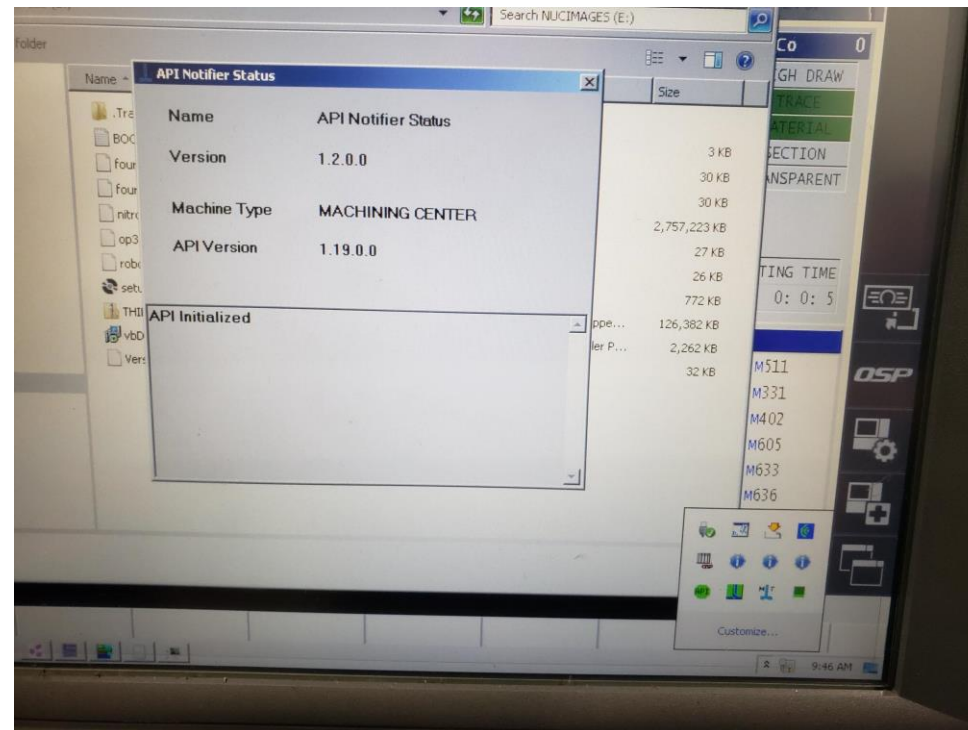
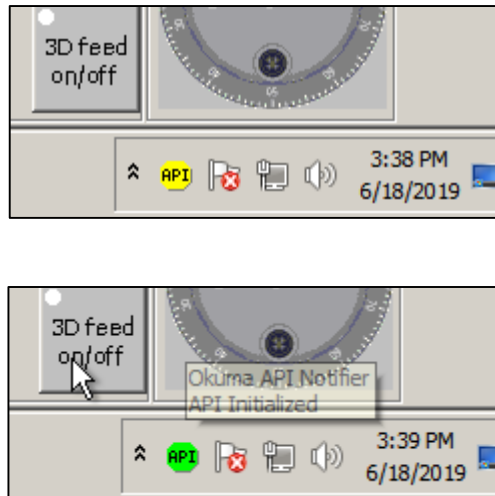
Software on Okuma Controller
Setup Okuma Settings on Robot2CNC



Update or Install ThincAPI on the Okuma CNC Controller

- ThincAPI is provided by Okuma:
 - Version 1.17.2 or newer is required

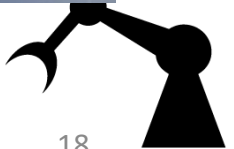
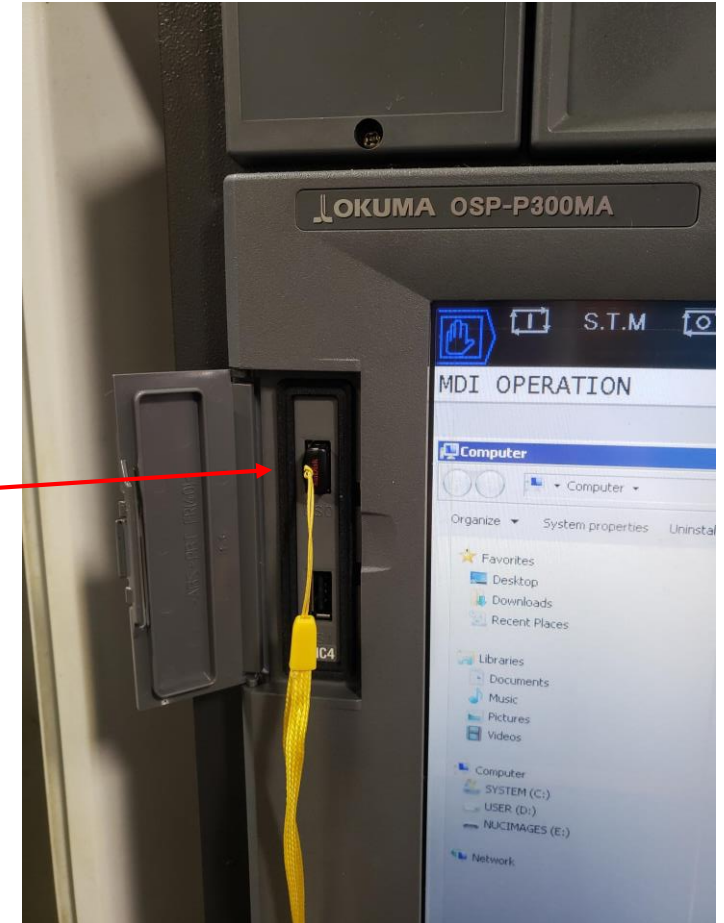
Successfully ThincAPI should show green API in the system tray when showing the windows screen.



Install CNC Programs to the Okuma CNC Controller

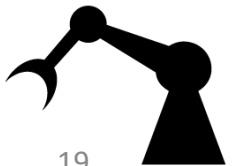
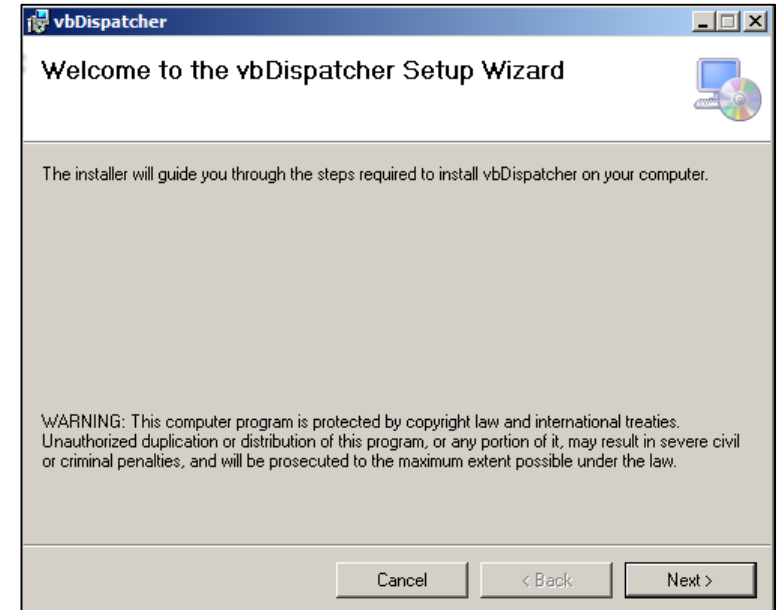
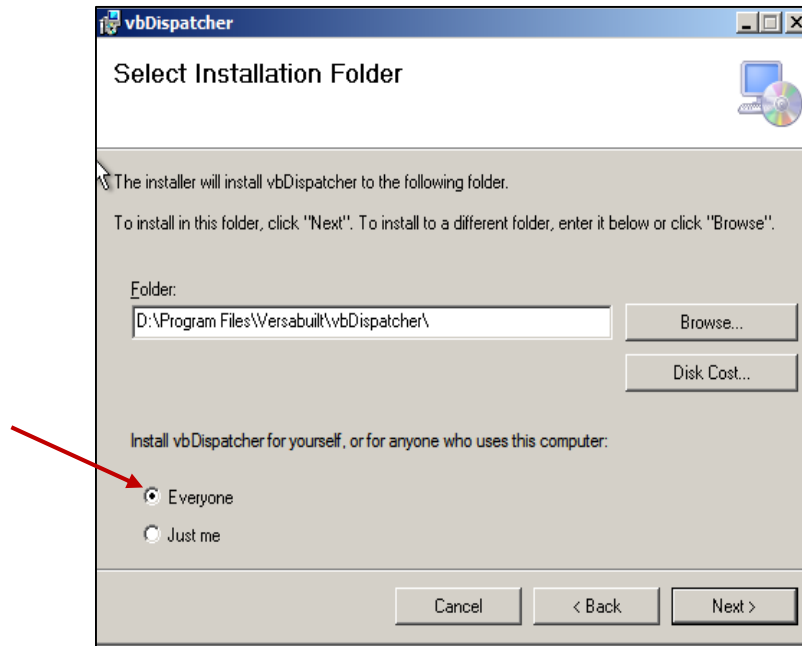
1. Plug VersaBuilt Robotics USB Thumb Drive into the CNC Controller
2. On the CNC enter the Windows portion of the CNC OS and open the folder for the USB Thumb Drive
3. Install the vbDispatcher program:
 - Two files for the Okuma vbDispatcher Program:
 - setup.exe
 - vbDispatcherSetup.msi

This VersaBuilt Robotics CNC program enables the Robot2CNC to communicate with the CNC.



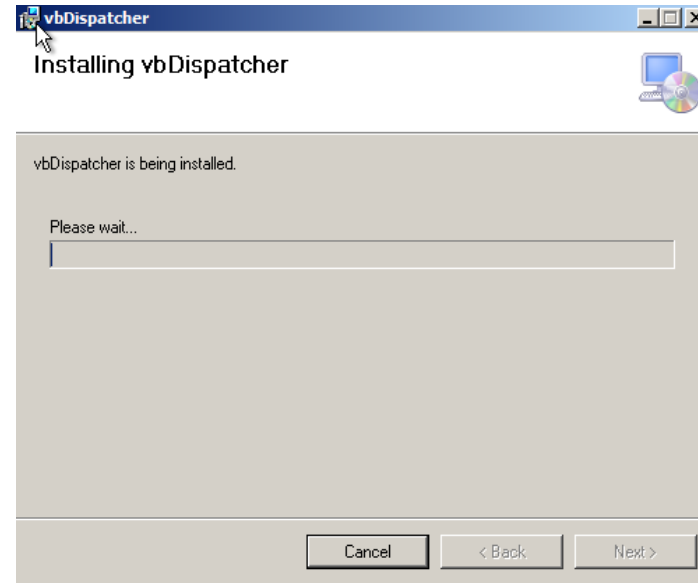
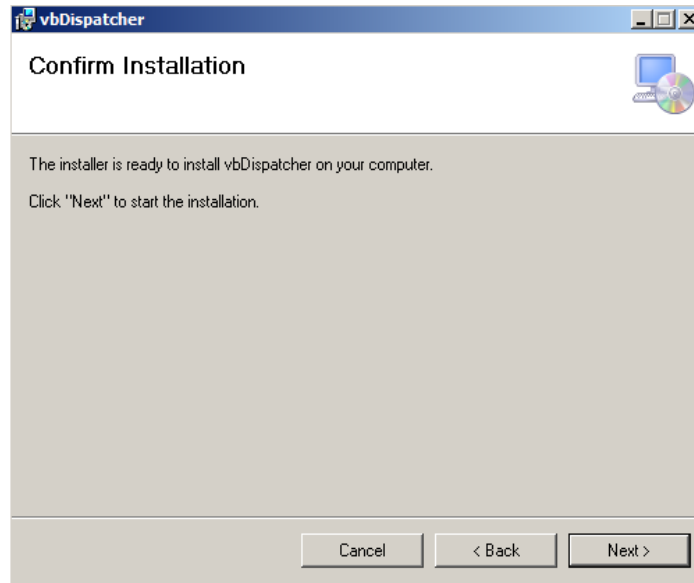
Install CNC Programs to the Okuma CNC Controller

- Run the vbDispatcherSetup.msi installer:
 - Click next to progress through installation
 - Defaults should work most of the time



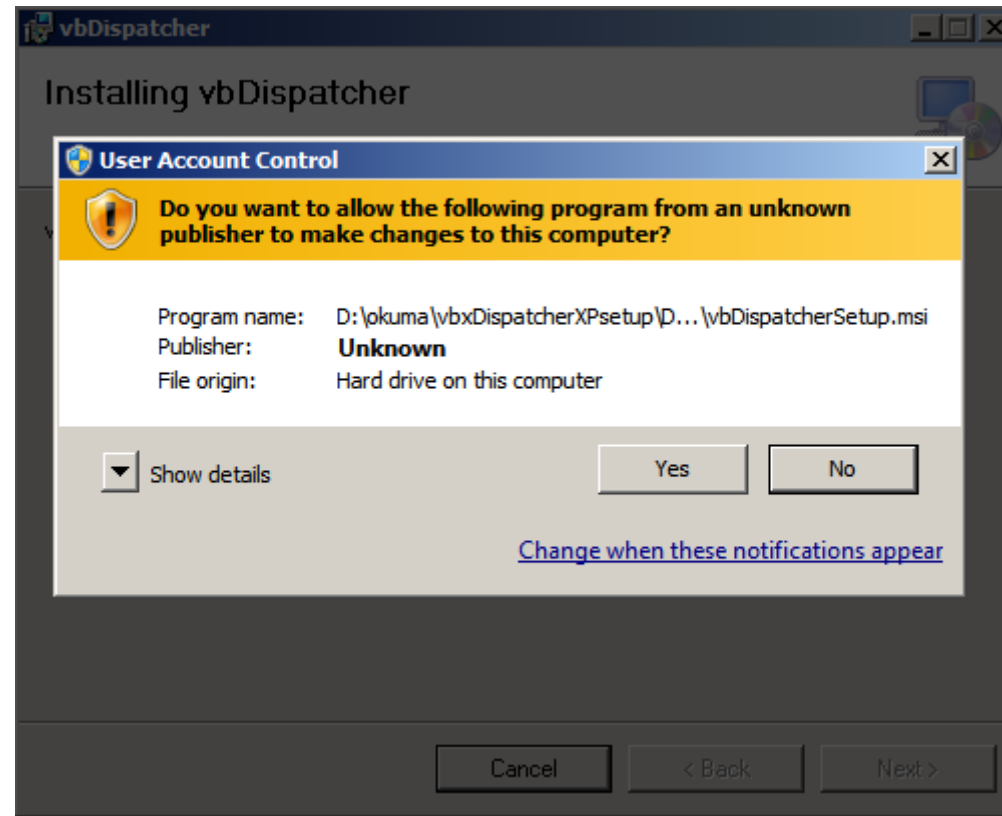
Install CNC Programs to the Okuma CNC Controller

- Click next to progress through installation



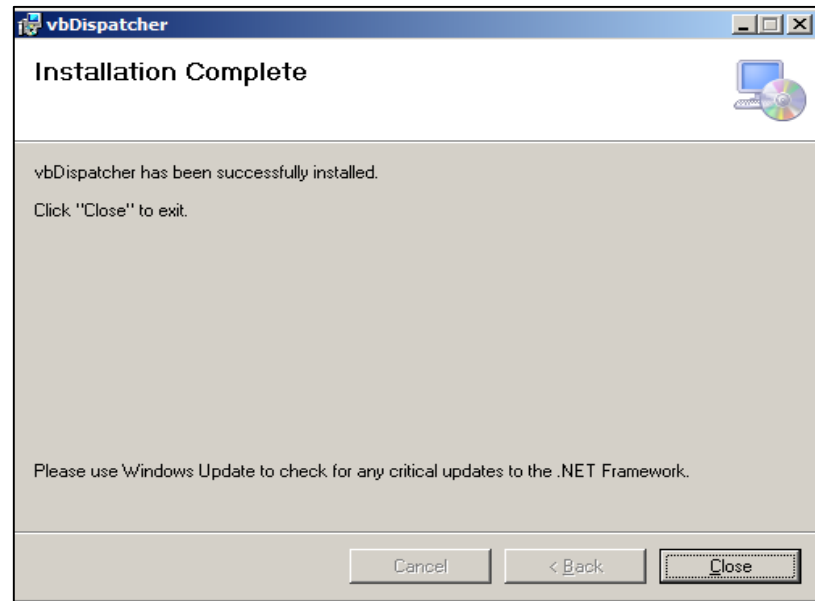
Install CNC Programs to the Okuma CNC Controller

- Click Yes to override User Account Control if prompted



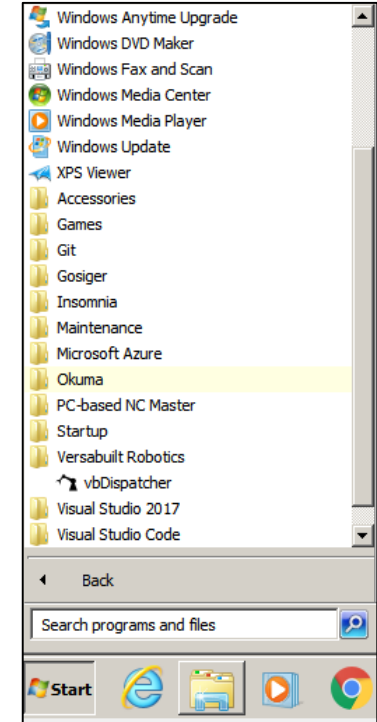
Install CNC Programs to the Okuma CNC Controller

- After installation is completed click Close



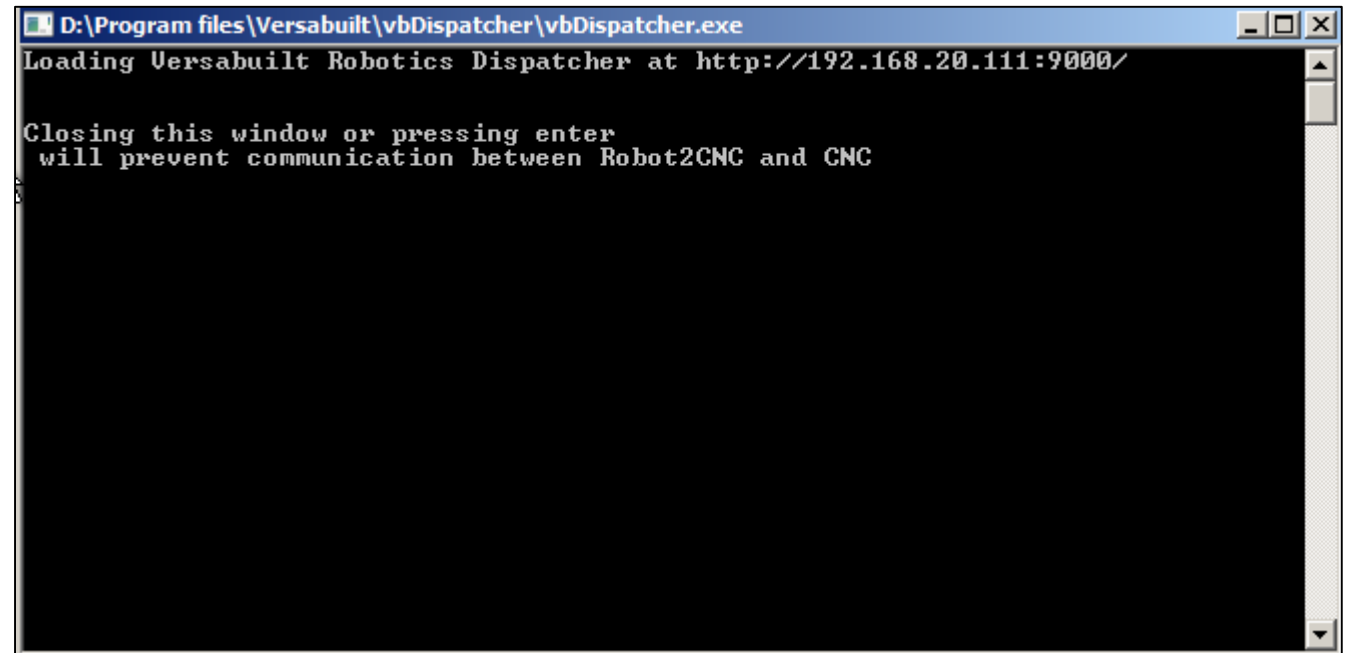
Install CNC Programs to the Okuma CNC Controller

- From the Start Menu, a new Versabuilt Robotics folder will show the vbDispatcher
- Click on vbDispatcher to run the required program for communication between Okuma CNC Controller and Robot2CNC



Install CNC Programs to the Okuma CNC Controller

- Running the vbDispatcher will present the following window. This window must remain open for communication to continue

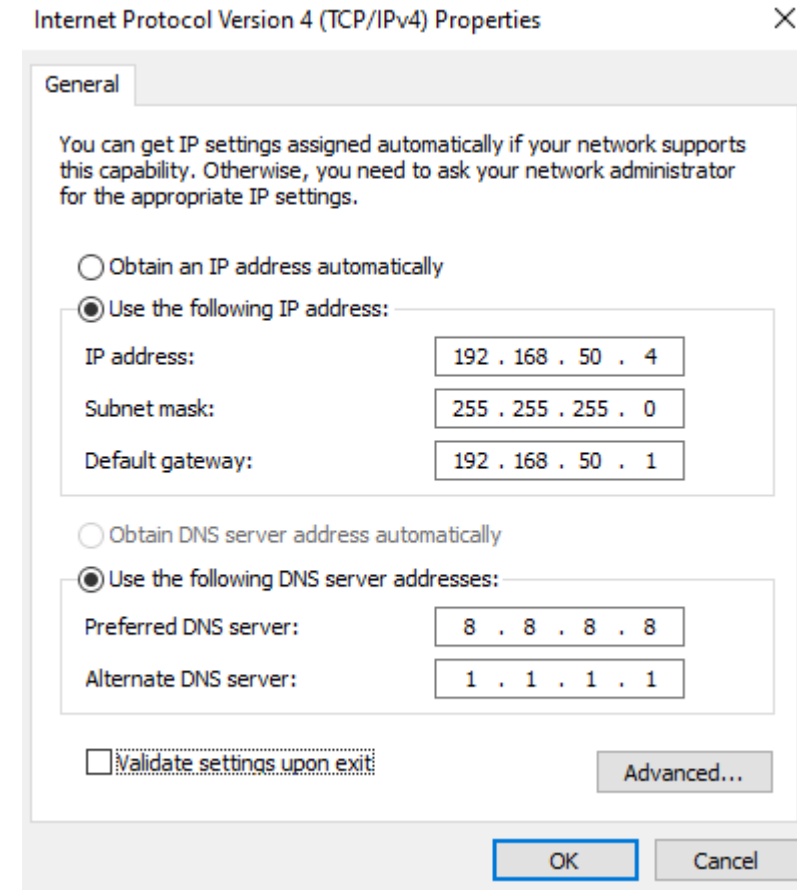


Setup Network via Windows on Okuma CNC

Setup a static network connection on the Okuma CNC using built in Microsoft Windows network setup

VersaBuilt recommended settings:

- IP Address: 192.168.50.4
- Subnet Mask: 255.255.255.0
- Gateway: 192.168.50.1



Internet Protocol Version 4 (TCP/IPv4) Properties

General

You can get IP settings assigned automatically if your network supports this capability. Otherwise, you need to ask your network administrator for the appropriate IP settings.

☐ Obtain an IP address automatically

☒ Use the following IP address:

IP address: 192 . 168 . 50 . 4

Subnet mask: 255 . 255 . 255 . 0

Default gateway: 192 . 168 . 50 . 1

☐ Obtain DNS server address automatically

☒ Use the following DNS server addresses:

Preferred DNS server: 8 . 8 . 8 . 8

Alternate DNS server: 1 . 1 . 1 . 1

☐ Validate settings upon exit

Advanced...

OK Cancel



Select Okuma CNC in Main System Settings

VERSABUILT
ROBOTICS Settings ▾

Main System Settings

REST API Port

9001

Text API Port

9002

CNC

Okuma ▾

IO

IO Shield ▾

Networker

On Board ▾

Save



CNC Settings

Using the main menu, choose CNC Configuration and validate that the settings match

VersaBuilt Robotics suggests the following settings

VERSABUILT
ROBOTICS CNC Configuration ▾

CNC Configuration

CNC IP Address

CNC Port Number

Cycle Start Address

Cycle Start Delay



Testing with Robot2CNC

Using the Robot2CNC to run CNC programs



Testing with Robot2CNC

Following the Robot2CNC Manual to access and setup the Robot2CNC

- Open the Home Page
- Basic Testing Can be accomplished on left side in the CNC Commands card
- Cycle Start should trigger the Cycle Start on the CNC
- Select Program will request the Okuma to select the program listed in the Text Box

VERSABUILT
ROBOTICS Home ▾

CNC Commands

Cycle Start

CNC Program

Select ProgramRun Program

Macro Variable Address

Read Macro Variable

Macro Variable Value

Write Macro Variable

August 2019

VersaBuilt Robotics

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A black silhouette of a robotic arm, specifically a SCARA-style arm, positioned in the bottom right corner of the slide.

Burn in Test

On the Right hand side of the Home Page the Activity and CNC Tests Card

Activity

Status

Complete

Since Jul 25th 2019, 2:42 pm

Update Status

CNC Tests

CNC Burn In Test

This test is used to run a CNC program a given number of times to confirm functionality and robust CNC communication.

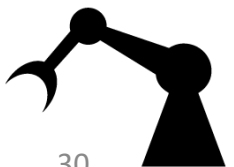
CNC Program

OTEST2

of Cycles

10

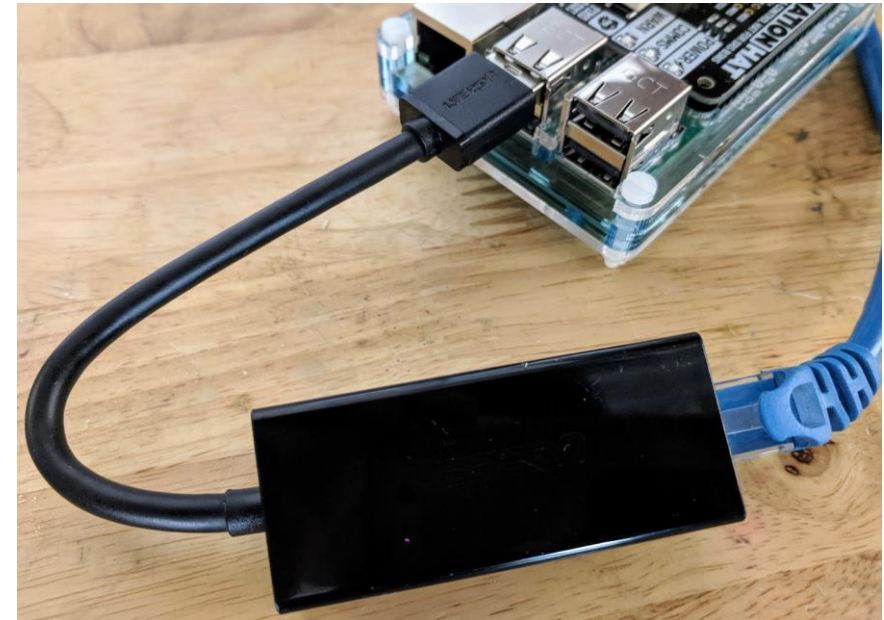
Run Test



Appendix A

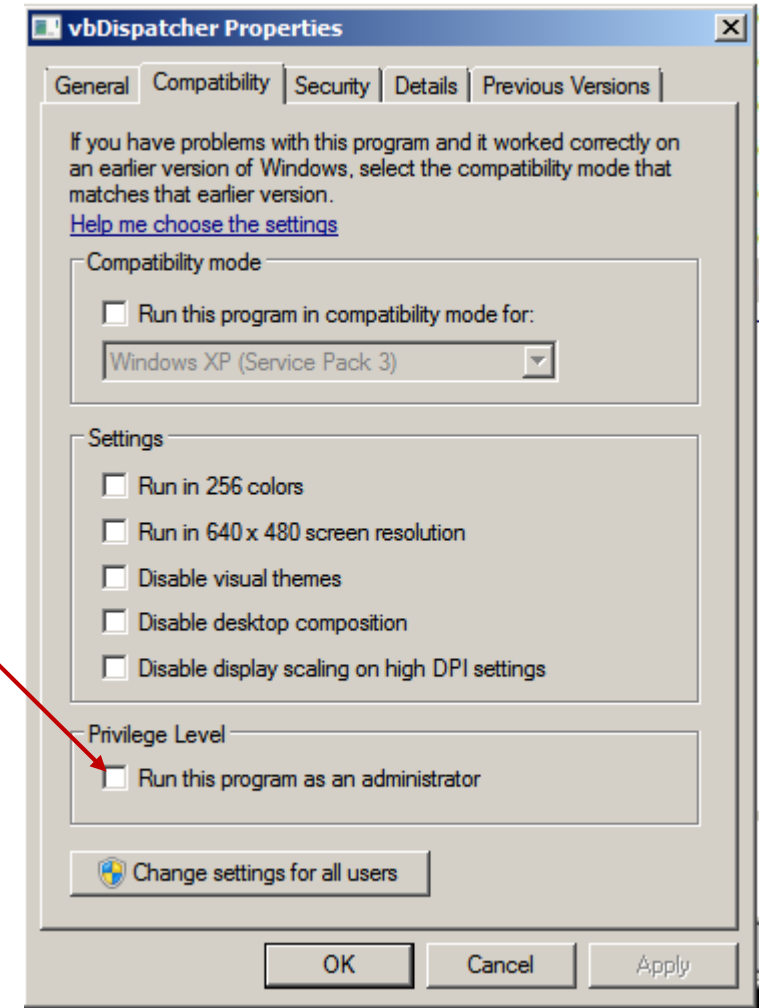
If your CNC is connected to your company network, please speak with your IT Administrator for correct setup and communication between VersaBuilt Robotics Robot2CNC, your CNC and your robot.

- The CNC will need a static IP address, the IT Administrator will provide:
 - CNC IP Address: This value will be entered into the CNC & the Robot2CNC
 - CNC Subnet Mask
- The Robot2CNC can use a dynamic or a static IP address
 - If Static, a System Administrator should provide Static IP address and valid Subnet Mask that should be setup on the Robot2CNC



Appendix B

- Administration Mode may be required to run successfully
 - From the install folder on the D drive, right click on the vbDispatcher.exe
 - Select the Compatibility tab
 - Check the box for “Run this program as administrator”



Appendix C

- Troubleshooting Connectivity:
 - The VersaBuilt Robotics Robot2CNC uses built-in procedures to communicate to the CNC
 - Verify the network cable is connected at each end to the appropriate controller
 - Verify IP Addresses
 - For further help troubleshooting connectivity, please contact helpdesk@versabuilt.com or 208-629-5914

